

THE ACTION OF THE MAPPING CLASS GROUP ON THE SPACE OF GEODESIC RAYS OF A PUNCTURED HYPERBOLIC SURFACE

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ABSTRACT. Let Σ be a complete finite-area orientable hyperbolic surface with one cusp, and let \mathcal{R} be the space of complete geodesic rays in Σ emanating from the puncture. Then there is a natural action of the mapping class group of Σ on \mathcal{R} . We show that this action is “almost everywhere” wandering.

1. INTRODUCTION

Let Σ be a complete finite-area orientable hyperbolic surface with one cusp, and \mathcal{R} the space of complete geodesic rays in Σ emanating from the puncture. Then, there is a natural action of the (full) mapping class group $\text{Map}(\Sigma)$ of Σ on $\mathcal{R} \equiv S^1$ (see Section 2). The dynamics of the action of an element of \mathcal{R} plays a key role in the Nielsen-Thurston theory for surface homeomorphisms. It also plays a crucial role in the variation of McShane’s identity for punctured surface bundles with pseudo-Anosov monodromy, established by [Bo1] and [AkMS].

It is natural to ask what does the action of the whole group $\text{Map}(\Sigma)$ (or its subgroups) look like. However, the authors could not find a reference which treats this natural question, though there are various references which study the action of (subgroups of) the mapping class groups on the projective measured lamination spaces, which are homeomorphic to higher dimensional spheres (see for example, [Mas1, Mas2, MccP, OS]). In particular, such an action is minimal (cf. [FatLP]) and moreover ergodic [Mas1].

The purpose of this paper is to prove that the action of $\text{Map}(\Sigma)$ on \mathcal{R} is “almost everywhere” wandering (see Theorem 2.1 for the precise meaning). This forms a sharp contrast to the above result of [Mas1].

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2. ACTIONS

Let $\Sigma = \mathbb{H}^2/\Gamma$ be a complete finite-area orientable hyperbolic surface with precisely one cusp, where $\Gamma = \pi_1(\Sigma)$. Let \mathcal{R} be the space of complete geodesic

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rays in Σ emanating from the puncture. Then \mathcal{R} is identified with a horocycle, τ , in the cusp. In fact, a point of τ determines a geodesic ray in Σ emanating from the puncture, or more precisely, a bi-infinite geodesic path with its positive end going out the cusp and meeting τ in the given point. Any mapping class ψ of Σ maps each geodesic ray to another path which can be “straightened out” to another geodesic ray, and hence determines another point of τ . This gives an action of the infinite cyclic group generated by ψ on $\mathcal{R} \equiv \tau$.

A rigorous construction of this action is described as follows. Choose a representative, f , of ψ , so that its lift \tilde{f} to the universal cover \mathbb{H}^2 is a quasi-isometry. Then \tilde{f} extends to a self-homeomorphism of the closed disc $\mathbb{H}^2 \cup \partial\mathbb{H}^2$. For a geodesic ray $\nu \in \mathcal{R}$, let $\tilde{\nu}$ be the closure in $\mathbb{H}^2 \cup \partial\mathbb{H}^2$ of a lift of ν to \mathbb{H}^2 . Then $\tilde{f}(\tilde{\nu})$ is an arc properly embedded in $\mathbb{H}^2 \cup \partial\mathbb{H}^2$, and its endpoints determine a geodesic in \mathbb{H}^2 , which project to another geodesic ray $\nu' \in \mathcal{R}$. Thus, we obtain an action of ψ on \mathcal{R} , by setting $\psi\nu = \nu'$. The dynamics of this action plays a key role in [AkMS]. However, one needs to verify that this action does not depend on the choice of a representative f of ψ .

In the following, we settle this issue, by using the canonical boundary of a relatively hyperbolic group described in [Bo2]. Though we are really interested here only in the case where the group is the fundamental group of a once-punctured closed orientable surface, and the peripheral structure is interpreted in the usual way (as the conjugacy class of the fundamental group of a neighborhood of the puncture), we give a discussion in a general setting.

Let Γ be a non-elementary relatively hyperbolic group with a given peripheral structure \mathcal{P} , which is a conjugacy invariant collection of infinite subgroups of Γ . By [Bo2, Definition 1], Γ admits a properly discontinuous isometric action on a path-metric space, X , with the following properties.

- (1) X is proper (i.e., complete and locally compact) and Gromov hyperbolic,
- (2) every point of the boundary of X is either a conical limit point or a bounded parabolic point,
- (3) the peripheral subgroups, i.e., the elements of \mathcal{P} , are precisely the maximal parabolic subgroups of Γ , and
- (4) every peripheral subgroup is finitely generated.

It is proved in [Bo2, Theorem 9.4] that the Gromov boundary ∂X is uniquely determined by (Γ, \mathcal{P}) , (even though the quasi-isometry class of the space X satisfying the above conditions is not uniquely determined). Thus the boundary $\partial\Gamma = \partial(\Gamma, \mathcal{P})$ is defined to be ∂X . By identifying Γ with an orbit in X , we obtain a natural topology on the disjoint union $\Gamma \cup \partial\Gamma$ which is compact Hausdorff, with Γ discrete and $\partial\Gamma$ closed.

The action of Γ on itself by left multiplication extends to an action on $\Gamma \cup \partial\Gamma$ by homeomorphism. This gives us a geometrically finite convergence action of Γ on $\partial\Gamma$. Let $\text{Aut}(\Gamma, \mathcal{P})$ be the subgroup of the automorphism group, $\text{Aut}(\Gamma)$, of Γ which respects the peripheral structure \mathcal{P} . This contains the inner automorphism

group, $\text{Inn}(\Gamma)$. Now, by the naturality of $\partial\Gamma$ ([Bo2, Theorem 9.4]), the action of $\text{Aut}(\Gamma, \mathcal{P})$ on Γ also extends to an action on $\Gamma \cup \partial\Gamma$, which is Γ -equivariant, i.e., $\phi \cdot (g \cdot x) = \phi(g) \cdot (\phi \cdot x)$ for every $\phi \in \text{Aut}(\Gamma, \mathcal{P})$, $g \in \Gamma$ and $x \in \Gamma \cup \partial\Gamma$. (In order to avoid confusion, we use \cdot to denote group actions, only in this place.) Under the natural epimorphism $\Gamma \rightarrow \text{Inn}(\Gamma)$, this gives rise to the same action on $\partial\Gamma$ as that induced by left multiplication. The centre of Γ is always finite, and for simplicity, we assume it to be trivial. In this case, we can identify Γ with $\text{Inn}(\Gamma)$.

Suppose that $p \in \partial\Gamma$ is a parabolic point. Its stabiliser, $Z = Z(\Gamma, p)$, in Γ is a peripheral subgroup. Now Z acts properly discontinuously cocompactly on $\partial\Gamma \setminus \{p\}$, so the quotient $T = (\partial\Gamma \setminus \{p\})/Z$ is compact Hausdorff (cf. [Bo2, Section 6]). Let $A = A(\Gamma, \mathcal{P}, p)$ be the stabiliser of p in $\text{Aut}(\Gamma, \mathcal{P})$. Then Z is a normal subgroup of A , and we get an action of $M = A/Z$ on T . If there is only one conjugacy class of peripheral subgroups, then the orbit Γp is $\text{Aut}(\Gamma, \mathcal{P})$ -invariant, and it follows that the group A maps isomorphically onto $\text{Out}(\Gamma, \mathcal{P}) = \text{Aut}(\Gamma, \mathcal{P})/\text{Inn}(\Gamma)$, so in this case we can naturally identify the group M with $\text{Out}(\Gamma, \mathcal{P})$.

Suppose now that Σ is a once-punctured closed orientable surface, with negative Euler characteristic $\chi(\Sigma)$. We write $\Sigma = D/\Gamma$, where $D = \tilde{\Sigma}$, the universal cover, and $\Gamma \cong \pi_1(\Sigma)$. Let \mathcal{P} be the peripheral structure of Γ arising from the cusp of Σ , namely \mathcal{P} consists of the conjugacy class of the fundamental group of a neighbourhood of the end of Σ . Then (Γ, \mathcal{P}) is a relatively hyperbolic group, because if we fix a complete hyperbolic structure on Σ then D is identified with \mathbb{H}^2 and the isometric action of Γ on $D = \mathbb{H}^2$ satisfies the conditions (1)–(4) in the above, namely [Bo2, Definition 1]. Now D admits a natural compactification to a closed disc, $D \cup C$, where C is the dynamically defined circle at infinity. We can identify C with $\partial\Gamma$. In fact, if x is any point of D , then identifying Γ with the orbit Γx , we get an identification of $\Gamma \cup \partial\Gamma$ with $\Gamma x \cup C \subseteq D \cup C$. As above we get an action of $\text{Aut}(\Gamma, \mathcal{P})$ on C . If $p \in \partial C$ is parabolic, then its stabiliser Z in Γ is isomorphic to the infinite cyclic group \mathbb{Z} , and we get an action of $\text{Out}(\Gamma, \mathcal{P})$ on the circle $T = (C \setminus \{p\})/Z$. Since $\text{Out}(\Gamma, \mathcal{P})$ is identified with the (full) mapping class group, $\text{Map}(\Sigma)$, of Σ , we obtain a well defined action of $\text{Map}(\Sigma)$ on the circle T .

We now return to the setting in the beginning of this section, where $\Sigma = \mathbb{H}^2/\Gamma$ is endowed with a complete hyperbolic structure. Then we can identify the (dynamically defined) circle T with the horocycle, τ , in the cusp, which in turn is identified with the space of geodesic rays, \mathcal{R} . This gives an action of $\text{Map}(\Sigma)$ on \mathcal{R} . Since the action of Γ on \mathbb{H}^2 satisfies the conditions (1)–(4) in the above (i.e., [Bo2, Definition 1]), we see that, for each mapping class ψ of Σ , its action on \mathcal{R} , defined via the “straightening process” presented at the beginning of this section, is identical with the action which is dynamically constructed in the above, independently from the hyperbolic structure. Thus the problem raised at the beginning of this section is settled.

In order to state the main result, we prepare some terminology. Let G be a group acting by homeomorphism on a topological space X . An open subset, $U \subseteq X$, is said to be *wandering* if $gU \cap U = \emptyset$ for all $g \in G \setminus \{1\}$. (Note that this definition is stronger than the usual definition of wandering, where it is only assumed that the number of $g \in G$ such that $gU \cap U \neq \emptyset$ is finite.) The *wandering domain*, $W_G(X) \subseteq X$ is the union of all wandering open sets. Its complement, $W_G^c(X) = X \setminus W_G(X)$, is the *non-wandering set*. This is a closed G -invariant subset of X . Note that if $Y \subseteq X$ is a G -invariant open set, then $W_G(Y) = W_G(X) \cap Y$. If $H \triangleleft G$ is a normal subgroup, we get an induced action of G/H on X/H . (In practice, the action of H on X will be properly discontinuous.) One checks easily that $W_G(X)/H \subseteq W_{G/H}(X/H)$ with equality if $W_H(X) = X$.

Note that any hyperbolic structure on Σ induces a euclidian metric on T (via the horocycle τ). If one changes the hyperbolic metric, the induced euclidian metrics on T are related by a quasimetry. However, they are completely singular with respect to each other (see [Ku, Tu2]). (That is, there is a set which has zero measure in one structure, but full measure in the other.) In general, this gives little control over how the Hausdorff dimension of a subset can change.

We say that a subset, $B \subseteq T$ is *small* if it has Hausdorff dimension strictly less than 1 with respect to any hyperbolic structure on Σ . Now we can state our main theorem.

Theorem 2.1. *Let Σ be a once-punctured closed orientable surface, with $\chi(\Sigma) < 0$, and consider the action of $\text{Map}(\Sigma)$ on the circle T , defined in the above. Then the non-wandering set in T with respect to the action of $\text{Map}(\Sigma)$ is small.*

In particular, the non-wandering set has measure 0 with respect to any hyperbolic structure, and so has empty interior.

Given that two different hyperbolic structures give rise to quasimetrically related metrics on T , it is natural to ask if there is a more natural way to express this. For example, is there a property of (closed) subsets of T , invariant under quasimetry and satisfied by the non-wandering set, which implies Hausdorff dimension less than 1 (or measure 0)?

3. THE LOOP-CUTTING CONSTRUCTION

Let $\Sigma = \mathbb{H}^2/\Gamma$ be a complete finite-area orientable hyperbolic surface with precisely one cusp, where $\Gamma = \pi_1(\Sigma)$. Thus the universal cover $D = \tilde{\Sigma}$ is identified with the hyperbolic plane \mathbb{H}^2 . Write C for the ideal boundary of D , which we consider equipped with a preferred orientation. Thus Γ acts on C as a geometrically finite convergence group. Let $\Pi \subseteq C$ be the set of parabolic points of Γ . Given $p \in \Pi$, let $\theta(p)$ be the generator of $\text{stab}_\Gamma(p)$ which acts on $C \setminus \{p\}$ as a translation in the positive direction. Given distinct $x, y \in C$, let $[x, y] \subseteq D \cup C$ denote the oriented geodesic from x to y . If $g \in \Gamma$ is hyperbolic, write $a(g), b(g)$ respectively, for its attracting and repelling fixed points; $\alpha(g) = [b(g), a(g)]$ for

its axis; and $\lambda(g)$ for the oriented closed geodesic in Σ corresponding to g , i.e., the image of $\alpha(g) \cap D$ in Σ . If $x, y \in C$ are distinct, then $[x, y] \cap D$ projects to an oriented bi-infinite geodesic path, $\lambda(x, y)$, in Σ . If $x, y \in \Pi$, then this is a proper geodesic path, with a finite number, $\nu(x, y)$, of self-intersections. Let $\Delta = \{(p, q) \in \Pi^2 \mid \nu(p, q) = 0\}$, i.e., Δ consists of pairs (p, q) of parabolic points such that $\lambda(p, q)$ is a proper geodesic arc. (By an *arc*, we mean an embedded path.) Given $p \in \Pi$, write $\Pi(p) = \{q \in \Pi \mid (p, q) \in \Delta\}$.

Pick an element $(p, q) \in \Delta$. Then the proper arc $\lambda(p, q)$ intersects a sufficiently small horocycle, τ , in precisely two points. Let $\tilde{\tau} \subseteq D$ be the horocircle centred at p which is a connected component of the inverse image of τ , and let $\{s_i\}_{i \in \mathbb{Z}}$ be the inverse image of the two points in $\tilde{\tau}$, located in this order, such that $s_0 = [p, q] \cap \tilde{\tau}$ and $\theta(p)s_i = s_{i+2}$. Then there is a unique element $g(p, q) \in \Gamma$ such that $g(p, q)p = q$ and $g(p, q)^{-1}[p, q] \cap \tilde{\tau} = s_1$. Namely, $g(p, q)^{-1}[p, q]$ is the closure of the lift of $\lambda(p, q)$ with endpoint p which is closest to $[p, q]$, among the lifts of $\lambda(p, q)$ with endpoint p , with respect to the preferred orientation of $\tilde{\tau}$. (See Figure 1.)

In the quotient surface Σ , the oriented closed geodesic $\lambda(g(p, q))$ is homotopic to the simple oriented loop obtained by shortcutting the oriented arc $\lambda(p, q)$ by the horocyclic arc which is the image of the subarc of $\tilde{\tau}$ bounded by s_0 and s_1 . Thus $\lambda(g(p, q))$ is a simple closed geodesic disjoint from the proper geodesic arc $\lambda(p, q)$. In particular, $[p, \theta(p)q] \cap \alpha(g(p, q)) = \emptyset$. In fact, the map $[(p, q) \mapsto g(p, q)] : \Delta \rightarrow \Gamma$ is characterised by the following properties: for all $(p, q) \in \Delta$, we have $g(p, q)p = q$, $g(q, p)g(p, q) = \theta(p)$, and $[p, \theta(p)q] \cap \alpha(g(p, q)) = \emptyset$.

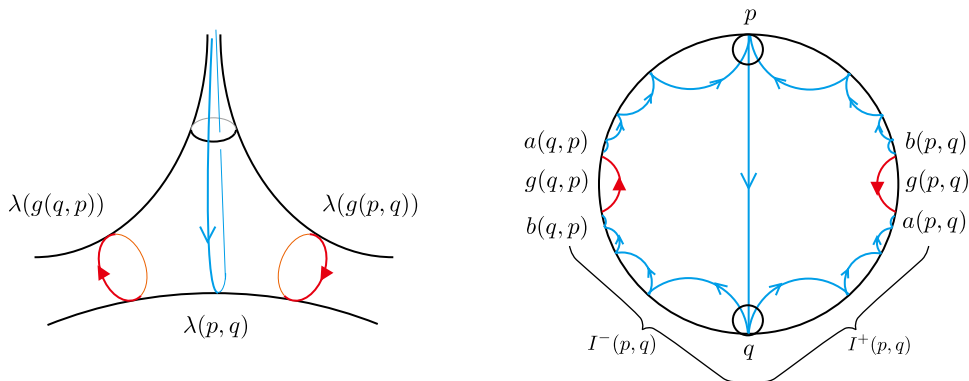


FIGURE 1. In the right figure, the two red arcs with thick arrows represent the axes $\alpha(g(p, q))$ and $\alpha(g(q, p))$ of the hyperbolic transformations $g(p, q)$ and $g(q, p)$ respectively. The blue arcs with thin arrows represent the oriented geodesic $[p, q]$ and its images by the infinite cyclic groups $\langle g(p, q) \rangle$ and $\langle g(q, p) \rangle$. The three intersection points of the blue arcs and the horocircle $\tilde{\tau}$ centred at p are s_{-1} , s_0 and s_1 , from left to right.

Write $a(p, q) = a(g(p, q))$ and $b(p, q) = b(g(p, q))$. Then the points $p, a(q, p), b(q, p), q, a(p, q), b(p, q)$ occur in this order around C . Let $I^+(p, q) = (q, a(p, q))$, $I^-(p, q) = (b(q, p), q)$ and $I(p, q) = (b(q, p), a(p, q))$ be open intervals in C . Thus $I(p, q) = I^-(p, q) \cup \{q\} \cup I^+(p, q)$, $I(p, q) \cap \theta(p)^n I(p, q) = \emptyset$ for all $n \neq 0$, and $I(p, q) \cap \theta(p)^n I(q, p) = \emptyset$ for all n .

In the quotient surface Σ , the oriented simple closed geodesics $\lambda(g(p, q))$ and $\lambda(g(q, p))$ cut off a punctured annulus containing the geodesic arc $\lambda(p, q)$, in which the simple geodesic rays $\lambda(p, a(p, q))$ and $\lambda(p, b(q, p))$ emanating from the puncture spiral to $\lambda(g(p, q))$ and $\lambda(g(q, p))$, respectively. Thus, each of $I^\pm(p, q)$ projects homeomorphically onto a *gap* in the horocircle τ , in the sense of [Mcs, p.610]. In fact, each of $I^\pm(p, q)$ is a maximal connected subset of $C \setminus \{p\}$ consisting of points x such that the geodesic ray $\lambda(p, x)$ is non-simple. Moreover, if $\lambda(p, x)$ is non-simple, then x is contained in $I^\pm(p, q)$ for some $q \in \Pi(p)$ (see [Mcs, TaWZ]).

Write $\mathcal{I}(p) = \{I(p, q) \mid q \in \Pi(p)\}$. Then we obtain the following as a consequence of [Mcs, Corollary 5] and [BiS] (see also [TaWZ, Section 5]):

Theorem 3.1. *The elements of $\mathcal{I}(p)$ are pairwise disjoint. The complement, $C \setminus \bigcup \mathcal{I}(p)$, is a Cantor set of Hausdorff dimension 0.*

Here, of course, the Hausdorff dimension is taken with respect to the euclidean metric on the horocycle, τ . Up to a scale factor, this is the same as the Euclidean metric in the upper-half-space model with p at ∞ . (Note that we could equally well use the circular metric on the boundary, C , induced by the Poincaré model, since all the transition functions are Möbius, and in particular, smooth.)

Write $R(p) = \{p\} \cup \Pi(p) \cup (C \setminus \bigcup \mathcal{I}(p)) \subseteq C$. This is a closed set, whose complementary components are precisely the intervals $I^\pm(p, q)$ for $q \in \Pi(p)$. Thus the set $R(p)$ is characterised by the following property: a point $x \in C$ belongs to $R(p)$ if and only if $x \neq p$ and the geodesic ray $\lambda(p, x)$ in Σ is simple.

For $p \in \Pi$, we define maps $\epsilon(p)$, $\mathbf{q}(p)$ and $\mathbf{g}(p)$ from $C \setminus R(p)$ to $\{+, -\}$, $\Pi(p)$ and Γ , respectively, by the following rule. If $x \in C \setminus R(p)$, then $x \in I^\epsilon(p, q)$ for some unique $\epsilon = \pm$ and $q \in \Pi(p)$. Define $\epsilon(p)(x) = \epsilon$, $\mathbf{q}(p)(x) = q$, and $\mathbf{g}(p)(x) = g(p, q)$ or $g(q, p)^{-1}$ according to whether $\epsilon = +$ or $-$. Note that the definition is symmetric under simultaneously reversing the orientation on C and swapping $+$ with $-$.

It should be noted that if $x \in C \setminus R(p)$, then, in the quotient surface Σ , the geodesic ray $\lambda(\mathbf{q}(p)(x), x) = \lambda(q, x)$ is obtained from the non-simple geodesic ray $\lambda(p, x)$ by cutting a loop, homotopic to $\lambda(\mathbf{g}(p)(x)) = \lambda(g(p, q))$, and straightening the resulting piecewise geodesic (see Figure 2). (In the quotient, we are allowing ourselves to cut out any peripheral loops that occur at the beginning.) In particular, if $x \in \Pi \setminus R(p)$, then both $\lambda(p, x)$ and $\lambda(\mathbf{q}(p)(x), x)$ are proper geodesic paths in Σ , and their self-intersection numbers satisfy the inequality $\nu(p, x) > \nu(\mathbf{q}(p)(x), x)$.

By repeatedly applying these maps, we associate for a given $x \in C$, a sequence $(g_i)_i$ in Γ , $(p_i)_i$ in Π , and $(\epsilon_i)_i$ in $\{+, -\}$ as follows.

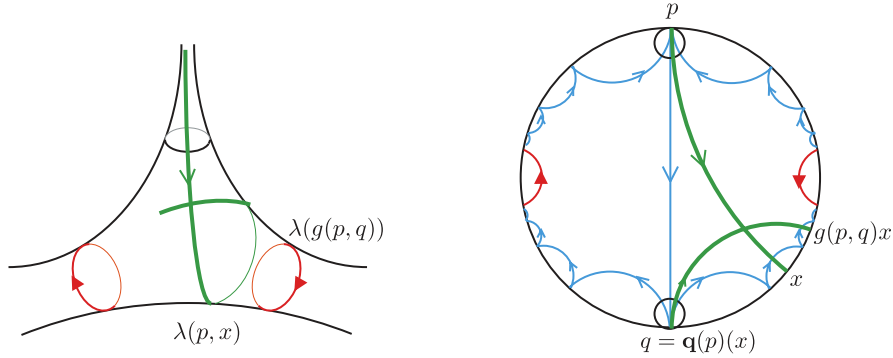


FIGURE 2. In the figure, we assume $\epsilon(p)(x) = +$ and so $\mathbf{g}(p)(x) = g(p, q)$.

Step 0. Pick a parabolic point $p \in \Pi$, and define $p_0 = p$. Thus, p_0 is independent of $x \in C$.

Step 1. If $x \in R(p_0)$, we stop with the 1-element sequence p_0 , and define $(g_i)_i$ and $(\epsilon_i)_i$ to be the empty sequence. If $x \notin R(p_0)$, set $g_1 = \mathbf{g}(p_0)(x)$, $p_1 = g_1 p_0$, $\epsilon_1 = \epsilon(p_0)(x)$, and continue to the next step. (The sequences $(g_i)_i$ and $(\epsilon_i)_i$ begin with index $i = 1$.)

Step 2. If $x \in R(p_1)$, we stop with the 1-element sequences g_1 and ϵ_1 and 2-element sequence p_0, p_1 . If $x \notin R(p_1)$, set $g_2 = \mathbf{g}(p_1)(x)$, $p_2 = g_2 p_1$ and $\epsilon_2 = \epsilon(p_1)(x)$.

We continue this process, forever or until we stop.

We call the resulting sequences $(g_i)_i$, $(p_i)_i$ and $(\epsilon_i)_i$ the *derived sequences* for x . More specifically, we call $(g_i)_i$ and $(p_i)_i$ the *derived Γ -sequence* and the *derived Π -sequence* for x , respectively.

Lemma 3.2. *Let $x \in C$, and let $(g_i)_i$, $(p_i)_i$ and $(\epsilon_i)_i$ be the derived sequences for x . Then the following hold.*

(1) *The sequences $(p_i)_i$ and $(\epsilon_i)_i$ are determined by the sequence $(g_i)_i$ by the following rule: $p_i = h_i p_0 = h_i p$ where $h_i = g_i g_{i-1} \cdots g_1$, and $\epsilon_i = +$ or $-$ according to whether $g_i = g(p_{i-1}, p_i)$ or $g(p_{i-1}, p_i)^{-1}$.*

(2) *A point $y \in C$ has the derived Γ -sequence beginning with g_1, g_2, \dots, g_n for some $n \geq 1$, if and only if $y \in \bigcap_{i=1}^n I^\epsilon(p_{i-1}, p_i)$.*

(3) *Set $R = \bigcup_{p \in \Pi} R(p)$. If $x \notin R$, then the derived Γ -sequence $(g_i)_i$ is infinite.*

(4) *If $x \in \Pi$, then the derived Γ -sequence $(g_i)_i$ is finite.*

Proof. (1), (2) and (3) follow directly from the definition of the derived sequences. To prove (4), let x be a point in Π . If $x \in R(p)$, then $(g_i)_i$ is the empty sequence. So we may assume $x \in \Pi \setminus R(p)$. Then by repeatedly using the observation made prior to the construction of the derived sequences, we see that the self-intersection number $\nu(p_i, x)$ of the proper geodesic path $\lambda(p_i, x)$ is strictly decreasing. Hence

$\nu(p_n, x) = 0$ for some n . This means that $x \in R(p_n)$ and so the derived sequences terminate at n . \square

The following is an immediate consequence of Lemma 3.2(2).

Corollary 3.3. *Suppose that $x \in C$ has derived Γ -sequence beginning with g_1, \dots, g_n for some $n \geq 1$. Then there is an open set, $U \subseteq C$, containing x , such that if $y \in U$, then g_1, \dots, g_n is also an initial segment of the derived Γ -sequence for y .*

Recall from Section 2 that $A(\Gamma, \mathcal{P}, p)$ denotes the subgroup of $\text{Aut}(\Gamma)$ preserving Π setwise and fixing $p \in \Pi$.

Lemma 3.4. *Let ϕ be an element of $A = A(\Gamma, \mathcal{P}, p)$ with $p = p_0$. Then the following holds for every point $x \in C$. If $(g_i)_i$, $(p_i)_i$ and $(\epsilon_i)_i$ are the derived sequences for x , then the derived sequences for ϕx are $(\phi(g_i))_i$, $(\phi p_i)_i$ and $(\deg(\phi)\epsilon_i)_i$.*

Proof. This can be proved through induction, by using the fact that the following hold for each $\phi \in A$.

- (1) $\phi(R(p)) = R(p)$.
- (2) For any $q \in \Pi(p)$, we have:
 - (a) If ϕ is orientation-preserving, then $\phi(\theta(p)) = \theta(p)$, $\phi(I^\epsilon(p, q)) = I^\epsilon(p, \phi(q))$, $\phi(g(p, q)) = g(p, \phi(q))$, and $\phi(g(q, p)) = g(\phi(q), p)$.
 - (b) If ϕ is orientation-reversing, then $\phi(\theta(p)) = \theta(p)^{-1}$, $\phi(I^\epsilon(p, q)) = I^{-\epsilon}(p, \phi(q))$, $\phi(g(p, q)) = g(\phi(q), p)^{-1}$, and $\phi(g(q, p)) = g(p, \phi(q))^{-1}$.

\square

4. FILLING ARCS

Let x be a point in C and $(p_i)_i$ the (finite or infinite) derived Π -sequence for x . Write $\lambda_i = \lambda(p_{i-1}, p_i)$ for the projection of $[p_{i-1}, p_i] \cap D$ to Σ . This is a proper geodesic arc in Σ . We call the sequence $(\lambda_i)_i$ the *derived sequence of arcs* for x . We say that x is *filling* if the arcs $(\lambda_i)_i$ eventually fill Σ , namely, there is some n such that $\Sigma \setminus \bigcup_{i=1}^n \lambda_i$ is a union of open discs. Let F be the subset of C consisting of points which are filling. In this section, we prove the following proposition.

Proposition 4.1. *The set F is open in C , and its complement has Hausdorff dimension strictly less than 1. In particular, F has full measure.*

We begin with some preparation. Let γ be a simple closed geodesic in Σ , and let $X(\gamma)$ be the path-metric completion of the component of $\Sigma \setminus \gamma$ containing the cusp. Then we can identify $X(\gamma)$ as $(H(G) \cap D)/G$, where $G = G(\gamma)$ is a subgroup of Γ containing $Z = \text{stab}_\Gamma(p)$, and $H(G) \subseteq D \cup C$ is the convex hull of the limit set $\Lambda G \subseteq C$. In other words, $X(\gamma)$ is the ‘‘convex core’’ of the hyperbolic surface \mathbb{H}^2/G . Note that $G = G(\gamma) \cong \pi_1(X(\gamma))$ and $p \in \Lambda G$.

Let δ be the closure of a component of $\partial H(G) \cap D$. This is a bi-infinite geodesic in $D \cup C$. Let $J \subseteq C$ be the component of $C \setminus \delta$ not containing p . Thus, J is an

open interval in C , which is a component of the discontinuity domain of G . Note in particular, that $J \cap Gp = \emptyset$.

Lemma 4.2. *Suppose $x \in J \setminus R(p)$, and let $g = \mathbf{g}(p)(x)$, $\epsilon = \epsilon(p)(x)$ and $q = \mathbf{q}(p)(x)$. Then, if $g \in G = G(\gamma)$, we have $J \subseteq I^\epsilon(p, q)$. In particular, $\mathbf{g}(p)(y) = g$ for every $y \in J$.*

Proof. To simplify notation we can assume (via the orientation reversing symmetry of the construction) that $\epsilon = +$. Note that $q \in Gp \subseteq \Lambda G$, so $[p, q] \subseteq H(G)$. Also $\alpha(g(p, q)) \subseteq H(G)$ and $\delta \subseteq \partial H(G)$. It follows that $[p, q]$, $\alpha(g(p, q))$ and δ are pairwise disjoint. Thus, J lies in a component of $Y := C \setminus \{p, q, a(p, q), b(p, q)\}$. Since $\epsilon = +$, the four points, $p, q, a(p, q), b(p, q)$ are located in C in this cyclic order, and so $I^+(p, q) = (q, a(p, q))$ is a component of Y . Since J and $I^+(p, q)$ share the point x , we obtain the first assertion that $J \subseteq I^\epsilon(p, q)$ with $\epsilon = +$. The second assertion follows from the first assertion and the definition of $\mathbf{g}(p)(y)$. \square

Lemma 4.3. *Suppose that $x \in J$ and that the derived Γ -sequence $(g_i)_i$ for x is infinite. Then there is some i such that $g_i \notin G = G(\gamma)$.*

Proof. Suppose, for contradiction, that $g_i \in G$ for all i . It follows that $h_i = g_i g_{i-1} \cdots g_1 \in G$ for all i , and so $p_i = h_i p \in Gp \subseteq \Lambda G$ for all i . By Lemma 4.2, we have $\mathbf{g}(p)(y) = \mathbf{g}(p)(x) = g_1$ for all $y \in J$. (Here $(p_i)_i$ is the derived Π -sequence for x and $p = p_0$.) Now, applying Lemma 4.2 with p_1 in place of p , we get that $\mathbf{g}(p_1)(y) = \mathbf{g}(p_1)(x) = g_2$. Continuing inductively we get that $\mathbf{g}(p_i)(y) = g_{i+1}$ for all i . In other words, the derived Γ -sequence for y is identical to that for x , and so, in particular, it must be infinite. We now get a contradiction by applying Lemma 3.2(4) to any point $y \in \Pi \cap J$. \square

If we take B to be a standard horoball neighbourhood of the cusp, then $B \cap \gamma = \emptyset$ for all simple closed geodesic in Σ , and so we can identify B with a neighbourhood of the cusp in any $X(\gamma)$.

Lemma 4.4. *There is some $\theta < 1$ such that for each simple closed geodesic, γ , the Hausdorff dimension of $\Lambda G(\gamma)$ is at most θ .*

Proof. This is an immediate consequence of [FalM, Theorem 3.11] (see also [Mat, Theorem 1]) which refines the result of [Tu1], on observing that the groups $G(\gamma)$ are uniformly “geometrically tight”, as defined in that paper. Here, this amounts to saying that there is some fixed $r \geq 0$ (independent of γ) such that the convex core, $X(\Gamma)$, is the union of B and the r -neighbourhood of the geodesic boundary of the convex core. From the earlier discussion, we see that r is bounded above by the diameter of $\Sigma \setminus B$, and so in particular, independent of γ . \square

Let $L \subseteq S$ be the union of the limit sets ΛG as $G = G(\gamma)$ ranges over all subgroups of Γ obtained from a simple closed geodesic γ in Σ . Applying Lemma 4.4, we see that L is a Γ -invariant subset of C of Hausdorff dimension strictly

less than 1. This is because it is a countable union of the limit sets ΛG whose Hausdorff dimensions are uniformly bounded by a constant $\theta < 1$.

Recall the set $R = \bigcup_{p \in \Pi} R(p)$ defined in Lemma 3.2(3). Then R is also Γ -invariant and has Hausdorff dimension zero by Theorem 3.1.

Lemma 4.5. *If $x \in C \setminus (R \cup L)$, then x is filling. Namely, $C \setminus (R \cup L) \subseteq F$.*

Proof. Suppose, for contradiction, that some $x \in C \setminus (R \cup L)$ is not filling. Then there must be some simple closed geodesic, γ , in Σ , which is disjoint from every λ_i , where $(\lambda_i)_i$ is the derived sequence of arcs for the point x . Consider the hyperbolic surface $X(\gamma)$ and its fundamental group $G = G(\gamma) \subseteq \Gamma$, as described at the beginning of this section. By hypothesis, $x \notin \Lambda G$, and so x lies in some component, J , of the discontinuity domain of G . By Lemma 4.3, there must be some $i \in \mathbb{N}$ with $g_i \notin G$. Choose the minimal such i . Thus, $h_{i-1} \in G$ but $h_i \notin G$, where $h_i = g_i g_{i-1} \cdots g_1$. We have $p_{i-1} = h_{i-1} p \in \Pi \cap \Lambda G$ and $p_i = h_i p \in \Pi \setminus \Lambda G$. (The latter assertion can be seen as follows. If $p_i \in \Lambda G$ then p_i is a parabolic fixed point of G . Since $X(\gamma)$ has a single cusp, there is an element $f \in G$ such that $p_i = f p_{i-1}$. Since $p_i = g_i p_{i-1}$, we have $f^{-1} g_i \in \text{stab}_\Gamma(p_{i-1}) = \text{stab}_G(p_{i-1})$. This implies $g_i \in fG \subseteq G$, a contradiction.) Therefore $[p_{i-1}, p_i]$ meets $\partial H(G)$, giving the contradiction that λ_i crosses γ in Σ . \square

Proof of Proposition 4.1. By Lemma 4.5, we have $C \setminus F \subseteq R \cup L$. Since R and L both have Hausdorff dimension strictly less than 1, the same is true of $C \setminus F$. Thus, we have only to show that F is open. Pick an element $x \in L$. Then there is some n such that $\Sigma \setminus \bigcup_{i=1}^n \lambda_i$ is a union of open discs, where $(\lambda_i)_i$ is a derived sequence of arcs for x . By Corollary 3.3, there is an open neighbourhood U of x in C such that every $y \in U$ shares the same initial derived Γ -sequence g_1, \dots, g_n with x . Thus, every $y \in U$ shares the same beginning derived sequence of arcs $(\lambda_i)_{i=1}^n$ with x . Hence every $y \in U$ is filling, i.e., $U \subseteq F$. \square

5. WANDERING

Recall that $\text{Map}(\Sigma)$ is identified with $M = A/Z$, where $A = A(\Gamma, \mathcal{P}, p)$ and $Z = Z(\Gamma, p)$, respectively, are the stabilisers of p in $\text{Aut}(\Gamma, \mathcal{P})$ and Γ . As described in Section 2, A acts on $C \setminus \{p\}$, and $\text{Map}(\Sigma) = M$ acts on the circle $T = (C \setminus \{p\})/Z$. The wandering domain $W_M(T)$ is equal to $W_A(C \setminus \{p\})/Z$, because $W_Z(C \setminus \{p\}) = C \setminus \{p\}$. (See the general remark on the wandering domain given in Section 2.)

Note that the set F in Proposition 4.1 is actually an open set of $C \setminus \{p\}$. For this set F , we prove the following lemma.

Lemma 5.1. $F \subseteq W_A(C \setminus \{p\})$.

Proof. We want to show that any $x \in F$ has a wandering neighbourhood. By assumption, some initial segment, $\lambda_1, \dots, \lambda_n$, of the derived sequence of arcs for x fills Σ . By Corollary 3.3, there is an open neighbourhood, U , of x , such that for every $y \in U$, the initial segment of length n of the derived sequence of arcs is

identical with $\lambda_1, \dots, \lambda_n$. Suppose that $U \cap \phi U \neq \emptyset$ for some non-trivial element ϕ of $\text{Map}(\Sigma) = A/Z$. Pick a point $y \in U \cap \phi U$ and set $x = \phi^{-1}y \in U$. By assumption, the derived sequences of arcs for both x and y begin with $\lambda_1, \dots, \lambda_n$. On the other hand, Lemma 3.4 implies that the derived sequence of arcs for $y = \phi x$ is equal to the image of that for x by ϕ . Hence we see that $\phi\lambda_i = \lambda_i$ for all $i = 1, \dots, n$. It follows by Lemma 5.2 below, that ϕ is the trivial element of $\text{Map}(\Sigma)$, a contradiction. \square

In the above, we have used the following lemma which appears to be well known, though we were unable to find an explicit reference.

Lemma 5.2. *Let $\lambda_1, \dots, \lambda_n$ be a set of proper oriented arcs in Σ which together fill Σ . Suppose that ψ is a mapping class on Σ fixing the proper homotopy class of each λ_i . Then ψ is trivial.*

Proof of Theorem 2.1. By Proposition 4.1, F is an open set of $C \setminus \{p\}$ whose complement has Hausdorff dimension strictly less than 1. Since $W_A(C \setminus \{p\})$ contains F by Lemma 5.1, its complement in $C \setminus \{p\}$ also has Hausdorff dimension strictly less than 1. Since $W_M(T) = W_A(C \setminus \{p\})/Z$, this implies that the non-wandering set, $T \setminus W_M(T)$, has Hausdorff dimension strictly less than 1. \square

Proof of Lemma 5.2. Fix any complete finite-area hyperbolic structure on Σ , and use it to identify $\tilde{\Sigma}$ with \mathbb{H}^2 . Construct a graph, M , as follows. The vertex set, $V(M)$, is the set of bi-infinite geodesics which are lifts of the arcs λ_i for all i . Two arcs $\mu, \mu' \in V(M)$ are deemed adjacent in M if either (1) they cross (that is, meet in \mathbb{H}^2), or (2) they have a common ideal point in $\partial\mathbb{H}^2$, and there is no other arc in $V(M)$ which separates μ and μ' . One readily checks that M is locally finite. Moreover, the statement that the arcs λ_i fill Σ is equivalent to the statement that M is connected. Note that $\Gamma = \pi_1(\Sigma)$ acts on M with finite quotient. Note also that M can be defined formally in terms of ordered pairs of points in $S^1 \equiv \partial\mathbb{H}^2$ (that is corresponding to the endpoints of the geodesics, and where crossing is interpreted as linking of pairs). The action of Γ on M is then induced by the dynamically defined action of Γ on S^1 .

Now suppose that $\psi \in \text{Map}(\Sigma)$. Lifting some representative of ψ and extending to the ideal circle gives us a homomorphism of S^1 , equivariant via the corresponding automorphism of Γ . Suppose that ψ preserves each arc λ_i , as in the hypotheses. Then ψ induces an automorphism, $f : M \rightarrow M$. Given some $\mu \in V(M)$, by choosing a suitable lift of ψ , we can assume that $f(\mu) = \mu$.

We claim that this implies that f is the identity on M . To see this, first let $V_0 \subseteq V(M)$ be the set of vertices adjacent to μ . This is permuted by f . Consider the order on V_0 defined as follows. Let I_R and I_L , respectively, be the closed intervals of S^1 bounded by $\partial\mu$ which lies to the right and left of μ . Orient each of I_R and I_L so that the initial/terminal points of μ , respectively, are those of the oriented I_R and I_L . Each $\nu \in V_0$ determines a unique pair $(x_R(\nu), x_L(\nu)) \in I_R \times I_L$ such that $x_R(\nu)$ and $x_L(\nu)$ are the endpoints of ν . Now we define the order \leq on

V_0 , by declaring that $\nu \leq \nu'$ if either (i) $x_R(\nu) \leq x_R(\nu')$ or (ii) $x_R(\nu) = x_R(\nu')$ and $x_L(\nu) \leq x_L(\nu')$. This order must be respected by f , because f preserves the orders on I_R and I_L . Since V_0 is finite, we see that $f|_{V_0}$ is the identity. The claim now follows by induction, given that M is connected.

It now follows that the lift of ψ is the identity on the set of all endpoints of elements of $V(M)$. Since this set is dense in S^1 , it follows that it is the identity on S^1 , and we deduce that ψ is the trivial mapping class as required. \square

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